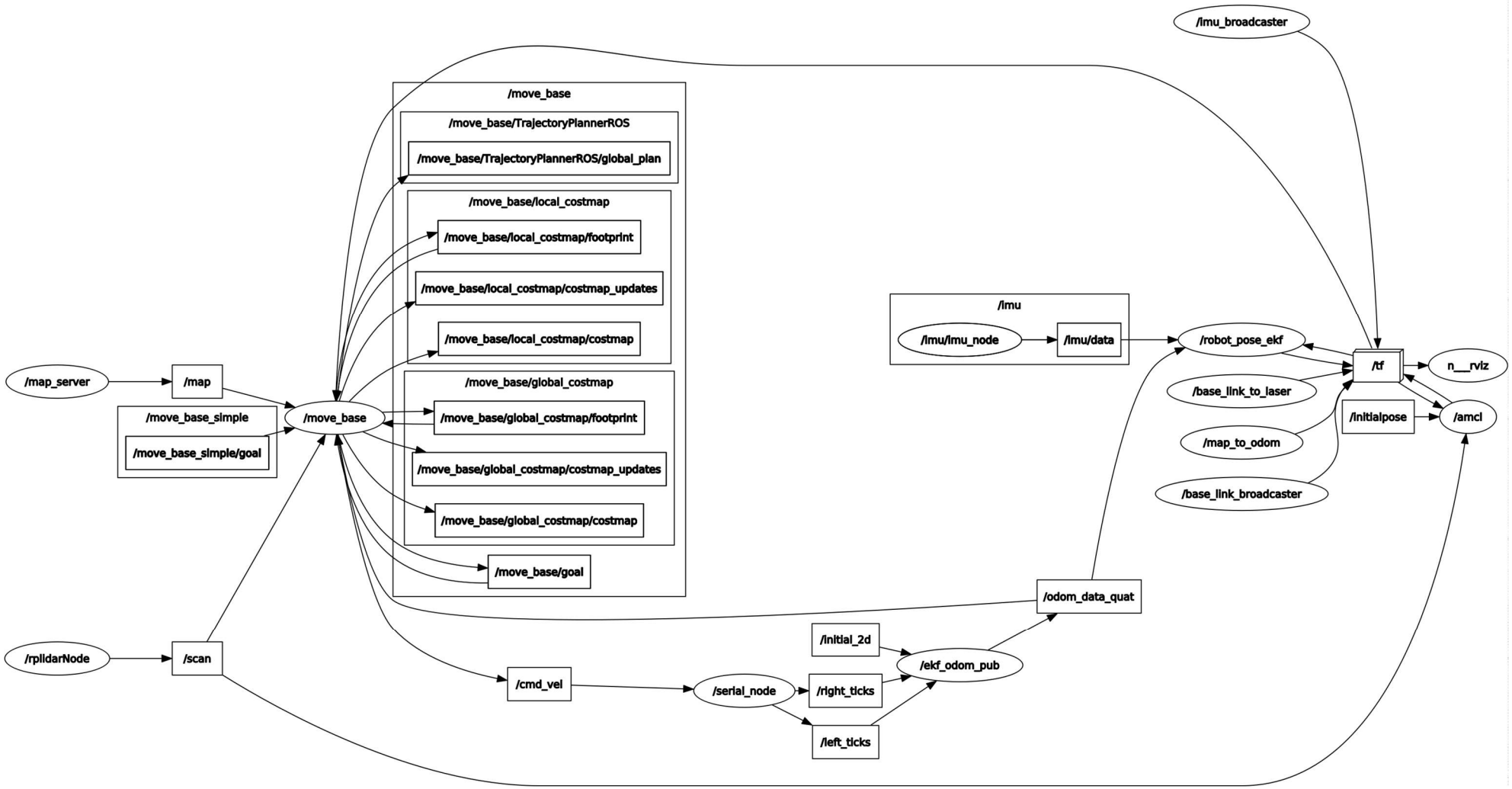
/imu_broadcaster
/move_base
/move_base/TrajectoryPlannerROS
/move_base/TrajectoryPlannerROS/global_plan
/move_base/local_costmap
/move_base/local_costmap/footprint
/move_base/local_costmap/costmap_updates
/move_base/local_costmap/costmap
/move_base/global_costmap
/move_base/global_costmap/footprint
/move_base/global_costmap/costmap_updates
/move_base/global_costmap/costmap
/move_base/goal
/imu
/imu/imu_node
/imu/data
/robot_pose_ekf
/tf
n__rviz
/base_link_to_laser
/initialpose
/amcl
/map_to_odom
/base_link_broadcaster
/map_server
/map
/move_base_simple
/move_base_simple/goal
/move_base
/odom_data_quat
/initial_2d
/ekf_odom_pub
/rplidarNode
/scan
/cmd_vel
/serial_node
/right_ticks
/left_ticks